

# Nathan Adkins

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## Education

**West Virginia University**, Morgantown, WV Aug 2021 - May 2025  
*Bachelor of Science in Computer Engineering (ABET), Minor in Computer Science, Minor in Economics*

## Internships & Experience

**WVU Interactive Robotics Laboratory**, Morgantown, WV

*NSF-Funded REU Researcher* May 2023 – Aug 2023

- Researched creating real-time human safety maps in retail spaces using an autonomous mobile robot.
- Integrated an autonomous navigation system utilizing LiDAR, IMU, and SLAM algorithms in ROS2.
- Created a custom library for Roboteq motor controllers, enabling modeling of robot wheel slip.

*Research Intern* May 2022 – Apr 2023

- Co-authored an IROS 2023 conference paper on swarm robotics and robotic morphogenesis.
- Lead development of the swarm system stack including ROS integration and hardware interfacing.

## Projects & Leadership

**WVU University Rover Challenge Team**, Morgantown, WV

*Algorithms Lead* Aug 2023 – May 2025

- Led the development of a robot autonomy stack for a mock-Mars environment, placing second internationally.
- Designed and tested an autonomy system with a global planner, local planner, and custom YOLO model.
- Built a React-based robot control interface including a map system, robot diagnostics, and live camera streams.
- Worked closely with mechanical engineers on sensor placement, addressing vibrations and sensor FOVs.

*Programming Lead* Aug 2022 – Jul 2023

- Led the development of a robot autonomy stack for a mock-Mars environment, achieving a first place victory.
- Developed a CAN and UART motor library in Python and C++ for use on robot manipulator and drivetrain motors.
- Gained experience integrating GPS and IMU in an autonomy stack.

*Programmer* Feb 2022 – Jul 2022

- Learned ROS and ROS2 through Python and C++ programming and hands-on robot testing.
- Gained proficiency in Ubuntu Linux by troubleshooting robot hardware and software.

## Awards

*Second Place, 2024 University Rover Challenge*

June 2024

*Statler Research Scholarship*

Fall 2023, Spring 2024

*First Place, 2023 University Rover Challenge*

June 2023

## Publications

*Jacobs, S., McAllister, R., Gillo, K., Cook, R., Wolf, T., Hassani, P., Ulbrich-Baker, J., Mapa, D., Adkins, N., McDonald, D., Chen, C., Gu, Y., "A Tale of Two Rovers: How Different Philosophies Foster Innovation in the 2023 University Rover Challenge," Column Paper, IEEE Robotics & Automation Magazine, Oct 2024*

*Smith, T., Butts, M., Adkins, N., Gu, Y., "Swarm of One: Bottom-up Emergence of Stable Robot Bodies from Identical Cells," IEEE/RSJ IROS 2023, Oct 2023.*

## Skills

**Languages:** Python, C, C++, JavaScript, MATLAB, SQL, Bash

**Software:** Ubuntu Linux, Git, ROS (Robot Operating System), ROS2, FreeRTOS, React, OpenCV

**Hardware:** GPS, IMU, LiDAR, Depth Cameras, Microcontrollers, UART, CAN, I2C

**Engineering:** System Integration, Technical Documentation, Software Design, Project Management